Modulating rotary actuator for ball
valves

- Nominal torque 4 Nm
- Nominal voltage AC/DC 24 V
- Control Modulating DC (0)0.5... 10 V
- Position feedback DC 0.5... 10 V
- Running time motor 9 s


Technical data

| Electrical data | Nominal voltage | AC/DC 24 V |
| :---: | :---: | :---: |
|  | Nominal voltage frequency | $50 / 60 \mathrm{~Hz}$ |
|  | Nominal voltage range | AC 19.2...28.8 V / DC 19.2...28.8 V |
|  | Power consumption in operation | 13 W |
|  | Power consumption in rest position | 2 W |
|  | Power consumption for wire sizing | 23 VA |
|  | Power consumption for wire sizing note | Imax 20 A @ 5 ms |
|  | Connection supply / control | Cable $1 \mathrm{~m}, 4 \times 0.75 \mathrm{~mm}^{2}$ |
|  | Parallel operation | Yes (note the performance data) |
| Functional data | Torque motor | Min. 4 Nm |
|  | Positioning signal $Y$ | DC 0... 10 V |
|  | Positioning signal Y note | Input impedance $100 \mathrm{k} \Omega$ |
|  | Operating range Y | DC 0.5... 10 V |
|  | Position feedback U | DC $0.5 \ldots .10 \mathrm{~V}$ |
|  | Position feedback U note | Max. 0.5 mA |
|  | Position accuracy | $\pm 5 \%$ |
|  | Manual override | Gear disengagement with push-button, can be locked |
|  | Running time motor | $9 \mathrm{~s} / 90^{\circ}$ |
|  | Adaption setting range | manual (automatic on first power-up) |
|  | Sound power level motor | $45 \mathrm{~dB}(\mathrm{~A})$ |
|  | Position indication | Mechanically, pluggable |
| Safety | Protection class IEC/EN | III Safety extra-low voltage |
|  | Protection class UL | UL Class 2 Supply |
|  | Degree of protection IEC/EN | IP54 |
|  | Degree of protection NEMA/UL | NEMA 2, UL Enclosure Type 2 |
|  | EMC | CE according to 2004/108/EC |
|  | Certification IEC/EN | IEC/EN 60730-1 and IEC/EN 60730-2-14 |
|  | Certification UL | cULus according to UL 60730-1A, UL 60730-214 and CAN/CSA E60730-1:02 |
|  | Mode of operation | Type 1 |
|  | Rated impulse voltage supply / control | 0.8 kV |
|  | Control pollution degree | 3 |
|  | Ambient temperature | $-30 . .40^{\circ} \mathrm{C}$ |
|  | Ambient temperature note | Caution: $+40 \ldots+50^{\circ} \mathrm{C}$ utilisation possible only under certain restrictions. Please contact your supplier. |
|  | Non-operating temperature | $-40 \ldots 80^{\circ} \mathrm{C}$ |
|  | Ambient humidity | 95\% r.h., non-condensing |
|  | Maintenance | Maintenance-free |
| Weight | Weight approx. | 0.92 kg |

## Safety notes



- This device has been designed for use in stationary heating, ventilation and air conditioning systems and is not allowed to be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.


## Safety notes

- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The switch for changing the direction of rotation may only be operated by authorised specialists. The direction of rotation must not in particular be reversed in a frost protection circuit.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- Self adaption is necessary when the system is commissioned and after each adjustment of the angle of rotation (press the adaption push-button once).
- The device contains electrical and electronic components and is not allowed to be disposed of as household refuse. All locally valid regulations and requirements must be observed.


## Product features

| Principle of operation | The actuator is connected with a standard modulating signal of DC $0 \ldots .10 \mathrm{~V}$ and travels <br> to the position defined by the positioning signal. Measuring voltage $U$ serves for the <br> electrical display of the valve position $0 \ldots 100 \%$ and as slave control signal for other <br> actuators. |
| :--- | :--- |
| Simple direct mounting |  |
| Manual override |  |
|  | Straightforward direct mounting on the ball valve with only one central screw. The <br> assembly tool is integrated in the plug-in position indication. The mounting orientation <br> in relation to the ball valve can be selected in $90^{\circ}$ steps. <br> Manual override with push-button possible (the gear is disengaged for as long as the <br> button is pressed or remains locked). |
| High functional reliability | The actuator is overload protected, requires no limit switches and automatically stops <br> when the end stop is reached. |
| Adjustable angle of rotation |  |
| Home position | Adjustable angle of rotation with mechanical end stops. <br> The first time the supply voltage is switched on, i.e. at the time of commissioning, <br> the actuator carries out an adaption, which is when the operating range and position <br> feedback adjust themselves to the mechanical setting range. |
|  | The detection of the mechanical end stops enables a gentle approach to the end <br> positions, thus protecting the actuator mechanics. |
| The actuator then moves into the position defined by the positioning signal. |  |
| Factory setting: Y2 (counter-clockwise rotation). |  |

## Accessories

|  | Description | Type |
| :--- | :--- | :--- |
| Electrical accessories | Auxiliary switch, add-on, $1 \times$ SPDT | S1A |
|  | Auxiliary switch, add-on, $2 \times$ SPDT | S2A |
|  | Feedback potentiometer 140 Ohm, add-on | P140A |
|  | Feedback potentiometer 200 Ohm, add-on | P200A |
|  | Feedback potentiometer 500 Ohm, add-on | P500A |
|  | Feedback potentiometer 1 kOhm, add-on | P2800A |
|  | Feedback potentiometer 2.8 kOhm, add-on | P5000A |
|  | Feedback potentiometer 5 kOhm, add-on | P10000 |

Electrical installation

| Notes $\quad$ - Connection via safety isolating transformer. |  |
| :--- | :--- |
|  | - Parallel connection of other actuators possible. Observe the performance data. |
|  | Direction of rotation switch is covered. Factory setting: Direction of rotation Y2. |

## Wiring diagrams

AC/DC 24 V , modulating


> Cable colours:
> $1=$ black
> $2=$ red
> $3=$ white
> $5=$ orange

Override control (frost protection circuit)


## Cable colours:

| c | d | Y1 / Y2 | Dov lou |
| :---: | :---: | :---: | :---: |
| L | - | $\mathrm{Y} 1 \sim$ | $A-A B=100 \%$ |
| - | - | $)_{1}$ | $A-A B=0 \%$ |
| - | 九 | DC (0) 0.5... 10 V |  |

$$
\begin{aligned}
& 1=\text { black } \\
& 2=\text { red } \\
& 3=\text { white } \\
& 5=\text { orange }
\end{aligned}
$$

Signal cable lengths


| $\mathrm{L}_{\mathbf{2}}$ | $\mathrm{L}_{\text {tot }}=\mathrm{L}_{1}+\mathrm{L}_{\mathbf{2}}$ |  |
| :---: | :---: | :---: |
|  | AC | DC |
| $0.75 \mathrm{~mm}^{2}$ | $\leq 30 \mathrm{~m}$ | $\leq 5 \mathrm{~m}$ |
| $1.00 \mathrm{~mm}^{2}$ | $\leq 40 \mathrm{~m}$ | $\leq 8 \mathrm{~m}$ |
| $1.50 \mathrm{~mm}^{2}$ | $\leq 70 \mathrm{~m}$ | $\leq 12 \mathrm{~m}$ |
| $2.50 \mathrm{~mm}^{2}$ | $\leq 100 \mathrm{~m}$ | $\leq 20 \mathrm{~m}$ |

A = actuator
$C=$ control unit
L1 = actuator connecting cable
L2 = customer cable
Ltot $=$ maximum signal cable length

## Note:

In the event of several actuators switched in parallel, the maximum signal cable length is to be divided by the number of actuators.

## Operating controls and indicators


(1) Direction of rotation switch

Switch over: Direction of rotation changes
2 Push-button and LED display green
Off: No power supply or malfunction
On: In operation
Press button: Triggers angle of rotation adaptation, followed by standard mode
(3) Push-button and LED display yellow

Off: Standard mode
On: Adaptation or synchronising process active
Press button: No function

## 4) Gear disengagement button

Press button: Gear disengages, motor stops, manual override possible
Release button: Gear engages, synchronisation starts, followed by standard mode
Check power supply connection
(2) Off and 3 On Possible wiring error in power supply

## Dimensions [mm]

Dimensional drawings


Further documentation

- Overview Valve-actuator combinations
- Data sheets for ball valves
- Installation instructions for actuators and/or ball valves
- General notes for project planning

