Communication-capable damper actuator for adjusting air dampers in ventilation and air conditioning systems in buildings

- Air damper size up to approx. $4 \mathrm{~m}^{2}$
- Torque 20 Nm
- Nominal voltage AC/DC 24 V
- Control modulating $4 \ldots 20 \mathrm{~mA}$
- Position feedback DC 2 ... 10 V or variable



## Technical data

Electrical data

| Nominal voltage | AC $24 \mathrm{~V}, 50 / 60 \mathrm{~Hz}$ / DC 24 V |  |  |
| :---: | :---: | :---: | :---: |
| Power supply range | AC 19.2 ... $28.8 \mathrm{~V} / \mathrm{DC} 21.6 \ldots 28.8 \mathrm{~V}$ |  |  |
| Power consumption In operation At rest For wire sizing | 3.5 W at nominal torque $1.25 \mathrm{~W}$ <br> 6 VA |  |  |
| Connection | Cable $1 \mathrm{~m}, 4 \times 0,75 \mathrm{~mm}^{2}$ |  |  |
| Functional data | Factory settings | Variable | Settings |
| Torque (nominal torque) | Min. 20 Nm at nominal voltage | 25\%, 50\%, $75 \%$ reduced |  |
| Control $\begin{array}{l}\text { Control signal } Y \\ \\ \text { Working range }\end{array}$ | 0 ... 20 mA , input impedance $500 \Omega$ <br> 4 ... 20 mA |  |  |
| Position feedback (measuring voltage U) | DC 2 ... 10 V , max. 0.5 mA | Start point DC $0.5 \ldots 8 \mathrm{~V}$ <br> End point DC $2.5 \ldots 10 \mathrm{~V}$ |  |
| Uni-rotation | $\pm 5 \%$ |  |  |
| Direction of rotation | Can be selected with 0 / 1 |  |  |
| Direction of motion at $\mathrm{Y}=0 \mathrm{~V}$ | In switch position $0 \sim$ or $1 \sim$ | Electronically reversible | - |
| Manual override | Disengaging the gearing latch by means of a pushbutton, self-resetting |  |  |
| Angle of rotation | Max. $95^{\circ}$ \&, can be limited at both ends with mechanical adjustable end stops |  |  |
| Running time | $150 \mathrm{~s} / 90^{\circ}$ ¢ | $86 \ldots 346$ s |  |
| Automatic adjustment of running time, operating range and measuring signal U to match the mechanical angle of rotation | Manual triggering of this adaption by pressing the button «Adaption» or with the PC-Tool | Automatic adaption whenever the supply voltage is switched on, or manual triggering |  |
| Override control | $\begin{aligned} \text { MAX (maximum position) } & =100 \% \\ \text { MIN (minimum position) } & =0 \% \end{aligned}$ | $\begin{aligned} & \text { MAX }=\left(\operatorname{MIN}+30^{\circ} \Varangle\right) \ldots 100 \% \\ & \text { MIN }=0 \% \ldots\left(\text { MAX }-30^{\circ} \Varangle\right) \end{aligned}$ |  |
| Sound power level | Max. 45 dB (A) | With a running $86 \mathrm{~s}=45 \mathrm{~dB}(\mathrm{~A})$ time of $\quad 346 \mathrm{~s}<35 \mathrm{~dB}(\mathrm{~A})$ |  |
| Position indication | Mechanical, plug-on |  |  |
| Safety |  |  |  |
| Protection class | III Safety extra-low voltage |  |  |
| Degree of protection | IP54 in all mounting positions |  |  |
| EMC | CE according to 2004/108/EC |  |  |
| Mode of operation | Type 1 (to EN 60730-1) |  |  |
| Rated impulse voltage | 0.8 kV (to EN 60730-1) |  |  |
| Control pollution degree | 3 (in acc. with EN 60730-1) |  |  |
| Ambient temperature range | $-30 \ldots+50^{\circ} \mathrm{C}$ |  |  |
| Non-operating temperature | $-40 \ldots+80^{\circ} \mathrm{C}$ |  |  |
| Ambient humidity range | 95\% r.H., non-condensating (to EN 60730-1) |  |  |
| Maintenance | Maintenance-free |  |  |
| Dimensions/weight |  |  |  |
| Dimensions | See «Dimensions» on page 3 |  |  |
| Weight | Approx. 910 g |  |  |



- The damper actuator is not allowed to be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- It may only be installed by suitably trained personnel.

All applicable legal or institutional installation regulations must be complied with.

- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- The cable is not allowed to be removed from the unit.
- When calculating the torque required, the specifications supplied by the damper manufacturers concerning the cross section, design and installation site, and the air flow conditions must be observed.
- The device contains electrical and electronic components and is not allowed to be disposed of as household refuse. All locally valid regulations and requirements must be observed.


## Product features

| Mode of operation | The actuator is controlled with a standard modulating signal of $4 \ldots 20 \mathrm{~mA}$ and travels to the <br> position defined by the control signal. Measuring voltage U serves for the electrical display of the <br> damper position $0 \ldots 100 \%$ and as slave control signal for other actuators. |
| :--- | :--- |
| Parameterisable actuators | The factory settings cover the most common applications. The output signal and other parameters <br> can be altered with the MFT-H parameterising device or the BELIMO Service Tool, MFT-P. |
| Simple direct mounting | Simple direct mounting on the damper spindle with a universal spindle clamp, supplied with an <br> anti-rotation strap to prevent the actuator from rotating. |
| Manual override | Manual operation with self-resetting pushbutton possible (the gear is disengaged for as long as <br> the button is pressed). |
| High functional reliability | Adjustable angle of rotation with mechanical end stops. <br> The actuator is overload-proof, requires no limit switches and automatically stops when the end <br> stop is reached. |
| Home position | When the supply voltage is switched on for the first time, i.e. at commissioning or after pressing <br> the "gear disengagement" switch, the actuator travels to the home position. |


| Pos. direction of <br> rotation switch | Home position |  |
| :--- | :--- | :--- |
| $\left.Z_{1}^{0}\right) \frac{\mathrm{Y}=0}{\mathrm{Y}=0 \curvearrowleft}$ | ccw | Left stop |

The actuator then moves into the position defined by the control signal.
Accessories

|  | Description | Data sheet |
| :---: | :---: | :---: |
| Electrical accessories | Auxiliary switch S..A.. | T2-S..A.. |
|  | Feedback potentiometer P..A.. | T2 - P..A.. |
|  | Manual parameterising device MFT-H | T2-MFT-H |
|  | PC-Tool MFT-P | T2 - MFT-P |
|  | Position sensor SG. 24 | T2-SG..24 |
|  | Digital position indication ZAD24 | T2-ZAD24 |
| Mechanical accessories | Various accessories (clamps, shaft extensions etc.) | T2-Z-SM..A.. |

## Electrical installation

| Wiring diagram/example |
| :--- | :--- |
| Note |
| - Connect via safety isolation transformer. |
| - Parallel connection of other actuators possible. |
| Note the performance data. |



Functions with basic values

## Master/Slave control



## Position indication



## Functional check



## Procedure

- Apply AC 24 V to connection 1 and 2
- Disconnect connection 6:
- For direction of rotation 0 :

Actuator turns in the direction of $\curvearrowleft$

- For direction of rotation 1:

Actuator turns in the direction of

- Short circuit connections 2 and 6:
- Actuator runs in the opposite direction


## Dimensions [mm]

Dimensional diagrams

| Damper spindle | Length | OT® |
| :--- | :--- | :--- |
| Clamp, top | Min. 42 | $10 \ldots 20(26,7)$ * |
| Clamp, bottom | Min. 20 | $10 \ldots 20$ |

* With K-ENSA as accessory



## Operating controls and indicators


(1) Direction of rotation switch

Switching over: Direction of rotation changes
(2) Pushbutton and green LED display

Off: $\quad$ No voltage supply or malfunction
Green on: Operation
Press button: Switches on angle of rotation adaption followed by standard operation
(3) Pushbutton and yellow LED display

Off: Standard operation
Yellow on: Adaption or synchronising process active
Press button: No function
(4) Gear disengagement switch

Press button: Gear disengaged, motor stops, manual operation possible
Release button: Gear engaged, synchronisation starts, followed by standard operation
(5) Service plug

For connecting parameterising and service tools


2


」.

AC 24 V / DC 24 V


SM24A..
AC $100 \ldots 240$ V


SM230A..


SM24A-S..


SM230A-S..


SM24AP5..



SM24A-MP..

AC $100 \ldots 240$ V



SM230A-V / VR..

