

## **Technical data sheet**

SR24ALON-5

# Rotary actuator for LONWORKS® for butterfly valves

- Torque 20 Nm
- Nominal voltage AC/DC 24 V
- Communications via LONWORKS® (FTT-10A)
- Conversion of sensor signals
- Integrated temperature controller



Technical data				
Electrical data				
Nominal voltage	AC 24 V, 50/60 Hz / DC 24 V			
Nominal voltage range	AC 19.2 28.8 V / DC 21.6 28.8 V			
Power consumption Operation	4 W @ nominal torque			
At rest	1.25 W			
For wire sizing	6 VA			
Connection	Cable 1 m, 6 x 0.75 mm <sup>2</sup>			
Data for LONWORKS®				
Certified	in accordance with LONMARK® 3.3			
Processor	Neuron 3150			
Transceiver	FTT-10A, compatible with LPT-10			
Functional Profile as per LONMARK®	Damper actuator object #8110			
	Open Loop Sensor Object #1			
	Thermostat Object #8060			
LNS plug-in for actuator / sensor / controller	Can be run with any LNS-based integration tool (min. for LNS 3.x)			
Service button and status LED	in accordance with guidelines LONMARK®			
Conductors, cables	Conductor lengths, cable specifications and			
	topology of the LONWORKS® network in			
	accordance with the ECHELON® guidelines			
Functional data	Factory settings	Variable	Setting	
Torque (nominal torque)	Min. 20 Nm @ nominal voltage 25 %, 50 %, 75 % reduced			
Position feedback (measuring voltage U)	DC 2 10 V, max. 0.5 mA	Start point DC 0.5 8 V End point DC 2.5 10 V		
Uni-rotation	±5% absolute			
Running time	90 s / 90°∢	90 s 346 s		
Automatic adjustment of running time,	Manual triggering of the adaption	Automatic adaption whenever the		
control and feedback to match the	by pressing the «Adaption» button	supply voltage is switched on, or		
mechanical angle of rotation	or with the PC-Tool	manual triggering		
Angle of rotation limiting	MAX (maximum position) = 100%	MAX = (MIN + 30° ⊲ ) 100%		
	MIN (minimum position) = 0%	MIN = $0\% (MAX - 30^{\circ})$		
	ZS (intermediate position, only AC) = $50\%$	ZS = MIN MAX		
Sound intensity	Max. 45 dB (A)	With a running time of $90 \text{ s} < 45 \text{ dE}$ 346  s = 35  c	· · ·	
Position indication	Mechanical, pluggable			
	Mechanical, pluggable	040 5 = 00 0		
Safety		0+0 5 = 00 0		
Safety Protection class	III Safety low voltage	0+0 5 = 00 0		
Safety Protection class Degree of protection	III Safety low voltage IP54 in any mounting position	0+0 5 = 00 0		
Safety Protection class Degree of protection EMC	III Safety low voltage IP54 in any mounting position CE according to 2004/108/EC	0+0 5 = 00 0		
Safety Protection class Degree of protection EMC Mode of operation	III Safety low voltage IP54 in any mounting position CE according to 2004/108/EC Type 1 (in acc. with EN 60730-1)			
Safety Protection class Degree of protection EMC Mode of operation Rated impulse voltage	III Safety low voltage IP54 in any mounting position CE according to 2004/108/EC Type 1 (in acc. with EN 60730-1) 0.8 kV (acc. to EN 60730-1)			
Safety         Protection class         Degree of protection         EMC         Mode of operation         Rated impulse voltage         Control pollution degree	III Safety low voltage IP54 in any mounting position CE according to 2004/108/EC Type 1 (in acc. with EN 60730-1) 0.8 kV (acc. to EN 60730-1) 3 (acc. to EN 60730-1)			
Safety         Protection class         Degree of protection         EMC         Mode of operation         Rated impulse voltage         Control pollution degree         Ambient temperature	III Safety low voltage           IP54 in any mounting position           CE according to 2004/108/EC           Type 1 (in acc. with EN 60730-1)           0.8 kV (acc. to EN 60730-1)           3 (acc. to EN 60730-1)           +0 +50 °C			
Safety         Protection class         Degree of protection         EMC         Mode of operation         Rated impulse voltage         Control pollution degree	III Safety low voltage IP54 in any mounting position CE according to 2004/108/EC Type 1 (in acc. with EN 60730-1) 0.8 kV (acc. to EN 60730-1) 3 (acc. to EN 60730-1)			

## SR24ALON-5

Rotary actuator LonWorks®, AC/DC 24 V, 20 Nm, for butterfly valves



Technical data	(continued)	
Safety		
Ambient humidity range	95% r.h., non-condensating (EN 60730-1)	
Maintenance	Maintenance-free	
Dimensions / Weight		
Dimensions	See «Dimensions» on page 3	
Weight	Approx. 1200 g	

## Safety notes

$\underline{\mathbb{N}}$	<ul> <li>The rotary actuator was designed for use in stationary, heating, ventilation and air conditioning systems and may not be used outside of the specific field of application, especially in aircraft or in any other airborne means of transport.</li> </ul>
	<ul> <li>It may only be installed by suitably trained personnel.</li> </ul>
	Any legal regulations or regulations issued by authorities must be observed during assembly.
	<ul> <li>The switch for changing the direction of rotation may only be operated by authorised personnel. The direction of rotation must not be reversed in a frost protection circuit.</li> </ul>
	<ul> <li>The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.</li> </ul>
	<ul> <li>The cable must not be removed from the device.</li> </ul>
	<ul> <li>The device contains electrical and electronic components and is not allowed to be disposed of as household refuse. All locally valid regulations and requirements must be observed.</li> </ul>

Product features	
Mode of operation	The actuator is equipped with an integrated interface for LONWORKS <sup>®</sup> . The actuator can be connected and controlled directly with LONWORKS <sup>®</sup> via transceiver FTT-10A.
Converter for sensors	Connection option for a sensor (passive or active sensor or switching contact). In this way, the analogue sensor signal can be easily digitised and transferred to LONWORKS <sup>®</sup> .
Integrated temperature controller	The actuator has an integrated temperature controller (Thermostat Object LONMARK <sup>®</sup> #8060). This makes it easy to implement individual room control solutions. The temperature controller can be set using the LNS Plug-In available from Belimo.
Parameterisable actuators	The factory settings cover the most common applications. As desired, individual parameters can be adapted for specific systems or servicing with an MFT parameterisation device (e.g. PC-Tool MFT-P).
Simple direct mounting	Simple direct mounting on a butterfly valve with ISO 5211 - F05 mounting flange. The mounting position in relation to the butterfly valve can be selected in 90° steps $\triangleleft$ .
Manual override	Manual control with pushbutton possible - temporary, permanently The gear is disengaged and the actuator decoupled for as long as the button is pressed / latched.
Adjustable angle of rotation	Adjustable angle of rotation with mechanical end stops.
High operational reliability	The actuator is overload-proof, requires no limit switches and automatically stops when the end stop is reached.
ISO 5211 - F05 Butterfly valve D6	For BELIMO F05 butterfly valve D6 and other dampers with the following mechanical specifications: - Square stem head (14 mm) for form-fit attachment of the rotary actuator. - Hole circle (d = 50 mm) for assembly with the butterfly valve.
Home position	When the supply voltage is switched on for the first time, i.e. at commissioning or after pressing the "gear disengagement" switch, the actuator moves to the home position.
	Rotary actuator         Rotary valve           Y1         A - AB = 0%

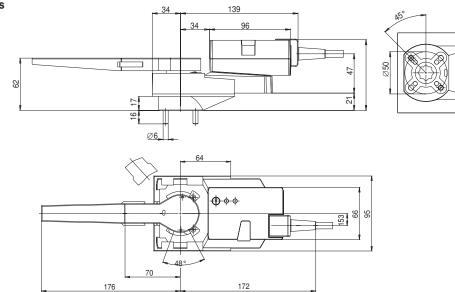
The actuator then moves into the position defined by LONWORKS®.

# Rotary actuator LonWorks®, AC/DC 24 V, 20 Nm, for butterfly valves



## Dimensions [mm]



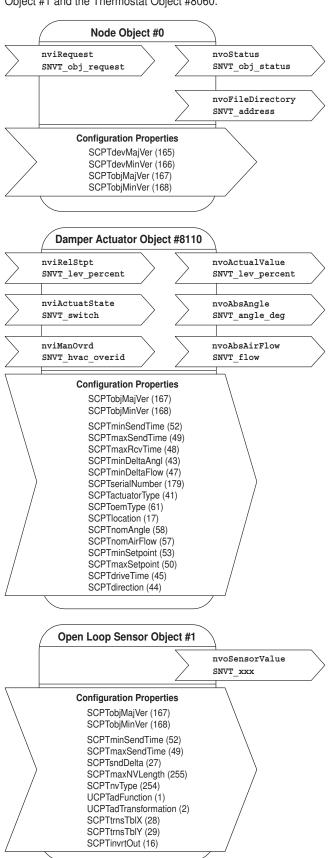


Further documentat	<ul> <li>Complete overview of actuators, water</li> <li>Data sheets for characterised control valves</li> <li>Installation instructions for actuators or ball valves, respectively</li> <li>Notes for project planning (hydraulic characteristic curves and circuits, installation regulations, commissioning, maintenance, etc.)</li> </ul>
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## Functional Profile as per LONMARK®

The LON-capable rotary actuator is certified by LONMARK<sup>®</sup>. Die following actuator functions are made available via the LONWORKS<sup>®</sup> network as standardised network variables in accordance with LONMARK<sup>®</sup>: the Node Object #0, the Damper Actuator Object #8110, the Open Loop Sensor Object #1 and the Thermostat Object #8060.



## Node object #0

The node object contains the object status and object request functions.

## nviRequest SNVT\_obj\_request

Input variable for requesting the status of a particular object in the node.

## nvoStatus SNVT\_obj\_status

Output variable that outputs the current status of a particular object in the node.

## nvoFileDirectory SNVT\_address

Output variable that shows information in the address range of the Neuron chip.

## Damper actuator object #8110

The actuator object is used to display the functions of the actuator on the page of the LONWORKS<sup>®</sup> network.

### nviRelStpt SNVT\_lev\_percent

The nominal position is assigned to the actuator via this input variable. This variable is normally linked to the output variable of an HVAC controller.

## nviActuateState SNVT\_switch

A preset position is assigned to the actuator via this input variable. Note on priority: The variable which was most recently active, either nviActuatorState or nviRelStpt, has priority.

## nviManOvrd SNVT\_hvac\_overid

This input variable can be used to manually override the actuator into a particular position.

## nvoActualValue SNVT\_lev\_percent

This output variable shows the current actual position of the actuator and can be used for control circuit feedback or for displaying positions.

## nvoAbsAngle SNVT\_angle\_deg

This output variable shows the current angle of rotation of the actuator and can be used to display the position or for service purposes.

### nvoAbsAirFlow SNVT\_flow

This output variable is inactive with this actuator and shows a constant value of 65535 (this variable is only active in conjunction with LON-capable VAV controllers).

## **Open Loop Sensor Object #1**

One sensor can be connected to the actuator.

A passive resistance sensor (e.g. Ni1000), an active sensor (output 0 ... 32 V) or a switch (On/Off) can be connected. In the case of the open loop sensor object, the measured sensor values are transferred to the LONWORKS<sup>®</sup> network.

## nvoSensorValue SNVT\_xxx

This output variable shows the current sensor value. Depending on the connected sensor, the output variable can be configured via the sensor plug-in and specifically adapted to the system.

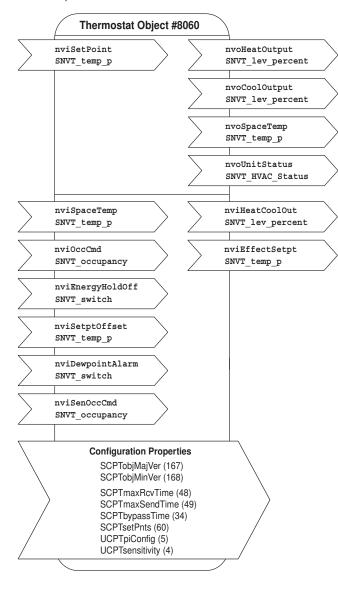
The SNVT can be configured as:		
SNVT_temp_p	SNVT_lev_percent	SNVT_lux
SNVT_temp	SNVT_abs_humid	SNVT_press_p
SNVT_switch	SNVT_enthalpy	SNVT_smo_obscur
SNVT_flow	SNVT_ppm	SNVT_power
SNVT_flow_p	SNVT_rpm	SNVT_elec_kwh



## Functional Profile as per LONMARK®

(continued)

Individual room control solutions can be implemented with the thermostat object LONMARK® #8060. An LNS plug-in is available for configuring the controller parameters.



## Note

A restart is necessary after accessing network variables for the purpose of rewriting them or after deleting links in order to initialise the variables.

## Thermostat Object #8060

#### nviSetPoint SNVT temp p

Setpoint specification for the controller from the higher-level system or the room control unit. If this variable is not linked, then the local setpoints of the controller object apply (can be adjusted via plug-in). The setpoint specification from the higher-level system influences the

setting on the controller as follows: Example: Comfort setpoint for heating = 21 °C and Comfort setpoint for cooling =  $23 \degree C$ . The median point between heating and cooling is thus 22 °C. Now, if the external setpoint (nviSetPoint ) is 23 °C, then the heating setpoint will shift to 22 °C and the cooling set point to 24 °C. The setpoints for Pre-Comfort heating and cooling will also be shifted accordingly.

#### nviSpaceTemp SNVT\_temp\_p

Room temperature from external room sensor. It is imperative that this variable be linked; typically, it is linked with the variable of the sensor object.

#### nviOccCmd SNVT\_occupancy

Occupancy specification from the command centre (for the function, see the table entitled «Functions Inputs Occupancy» page 5).

#### nviEnergyHoldOff SNVT switch

In the case of active EnergyHoldOff, the controller will be set to the Building Protection setpoints.

#### nviSetPtOffset SNVT temp p

Shifting of the room control unit. If the nviSetPoint is linked, then this input has an influence on the variable value of nviSetPoint, i.e. it corrects it. Otherwise, the Comfort and Pre-Comfort setpoints for heating and cooling will be adjusted directly by the amount of the shift (compare example with nviSetPoint).

#### nviDewpointAlarm SNVT\_switch

In the case of active DewpointAlarm, the controller will be set to the Building Protection setpoints. The cooling sequence is deactivated.

#### nviSenOccCmd SNVT\_occupancy

Occupancy specification from the local occupancy switch (for the function, see the table entitled «Functions Inputs Occupancy» page 5).

#### nvoHeatOutput SNVT lev percent

Control signal for heating.

#### nvoCoolOutput SNVT\_lev\_percent

Control signal for cooling.

#### nvoSpaceTemp SNVT\_temp\_p

Displays the room temperature of the nviSpaceTemp. If nviSpaceTemp is not linked, then the variable will display the value 0x7FFF.

#### **SNVT HVAC Status** nvoUnitStatus

Displays the operating mode of the controller (in accordance with Functional Profile #8060)

#### nvoHeatCoolOut SNVT lev percent

Depicts the heating and cooling sequence for controlling the 6-way characterised control valves (see illustration, page 5).

This outlet runs parallel to the nvoCoolOutput or the nvoHeatOutput, respectively.

Cooling = 33 ... 0% Valve closed 33 ... 66% Heating = 66 ... 100%

## nvoEffectSetpt

SNVT temp p Shows the actual setpoint of the controller. Note



Functional Profile as per LONMARK <sup>®</sup> C
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The function nviOccCmd has a higher priority than

the function nviSenOccCmd.

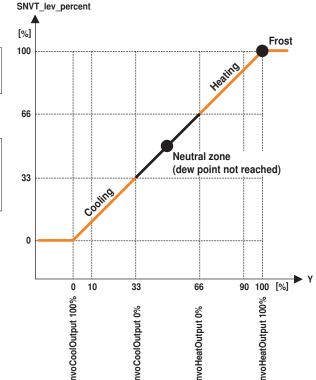
## **Functions Inputs Occupancy**

## ontinued

nvoHeatCoolOut

#### Occupancy specification Room operating **Occupancy switch** Comfort extension from nviOccCmd nviSenOccCmd status command centre OC\_OCCUPIED OC\_OCCUPIED Comfort OC UNOCCUPIED Comfort OC\_NUL (default) Comfort OC\_STANDBY OC\_OCCUPIED **Bypass** Occupied time is extended by the amount of the bypass time (comfort time) (can be adjusted in the plug-in) OC UNOCCUPIED Pre-comfort OC\_NUL (default) Pre-comfort OC\_UNOCCUPIED OC\_OCCUPIED **Building protection** OC\_UNOCCUPIED **Building protection Building protection** OC\_NUL (default) OC\_NUL (default) OC\_OCCUPIED Comfort OC\_UNOCCUPIED Pre-comfort OC\_NUL (default) Comfort

## Function nvoHeatCoolOut



Heating / cooling with Belimo 6-way characterised control valve.

Typical application

Note chilled ceiling application In the case of active DewPointAlarm (nviDewPointAlarm), the controller will be set to the Building Protection setpoints. The cooling sequence is deactivated.

## Notes

More detailed information on the functional profiles can be found on the website of LONMARK® (www.lonmark.org)



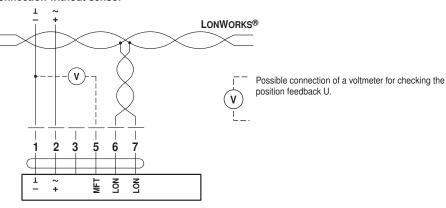
## **Electrical installation**

Note Connect via safety isolation transformer.

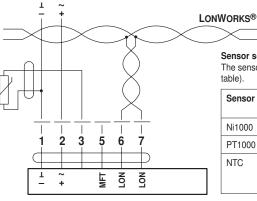
Wiring diagrams

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Connection without sensor



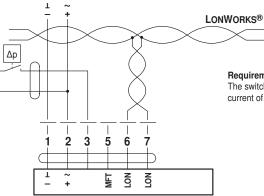
## Connection with passive sensor, e.g. Pt1000, Ni1000, NTC



Sensor scaling: The sensors can be scaled with the sensor plug-in (sensor table).

Sensor	Temperature range	Resistance range	Resolution
Ni1000	–28 +98°C	850 1600 Ω	1 Ω
PT1000	−35 +155°C	850 1600 Ω	1Ω
NTC	-10 +160°C (depending on type)	200 60 kΩ	1 Ω

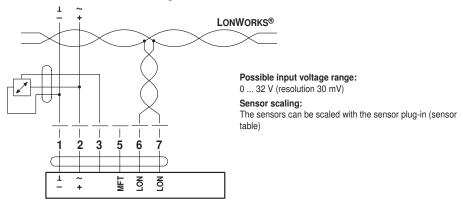
### Connection with switching contact, e.g. Ap-monitor



Requirements for switching contact: The switching contact must be able to accurately switch a

current of 16 mA at 24 V.

Connection with active sensor, e.g. 0 ... 10 V @ 0 ... 50 °C



Actuator for LONWORKS®, AC/DC 24 V

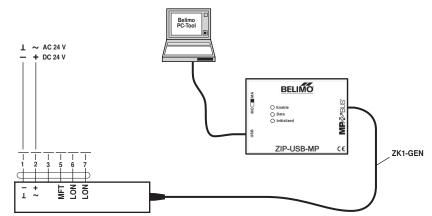


## Parameterisation

Connection of the MFT parameterising devices, e.g. Belimo PC-Tool MFT-P

- The actuator can be parameterised as follows:
- Electronic angle of rotation limiting
  - Torque reduction
  - Operation mode cw/ccw
  - Running time
  - Function test or adaption can be triggered
  - Position feedback (measuring voltage U)

### Parameterisation of the connected actuator



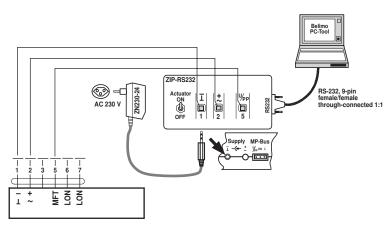
# Notes • The actuator can be triggered with the PC-Tool

- under "PP". • The USB cable is included in the ZIP-USB-MP
- scope of delivery.
- The connection cable ZK1-GEN has to be ordered separately.

### Parameterisation of the actuator, Standalone, without AC/DC 24V supply

## Notes

- The actuator can be triggered with the PC-Tool under "PP".
- The RS-232 cable is included in the ZIP232 scope of delivery.
- The power supply unit ZN230-24 has to be ordered separately.



## **Operating controls and indicators**



### **1** Direction of rotation switch

Switching over: Direction of rotation changes

- (2) Push-button and green LED display
  - No voltage supply or fault
  - Operation
  - Press button: Switches on angle of rotation adaptation followed by standard operation
- (3) Service button for commissioning with LONWORKS® and LED display yellow for LON status

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	Off:	The actuator is integrated ready-for-operation in the LONWORKS <sup>®</sup> network.
	On:	No application software is loaded in the actuator.
	Blinking:	The actuator is ready-for-operation, but not integrated in the LONWORKS®
	(flashing interval 2 s)	network (unconfigured).
	Other flashing codes:	A fault is present in the actuator.
	Press button:	Service Pin Message will be sent to the LONWORKS® network.
<b>(4</b> )	Gearing latch key	
U	acaring laten key	
	Press button:	Gear disengaged, motor stops, manual override possible

Gear disengaged, motor stops, manual override possible Gear engaged, synchronisation starts, followed by standard operation

## 5 Service plug

Release key:

Off:

On:

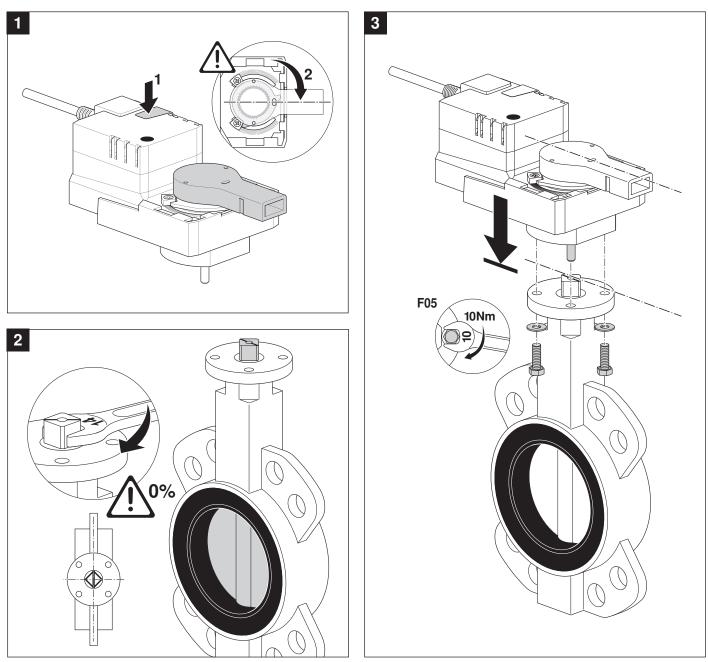
For connecting parameterising and service tools

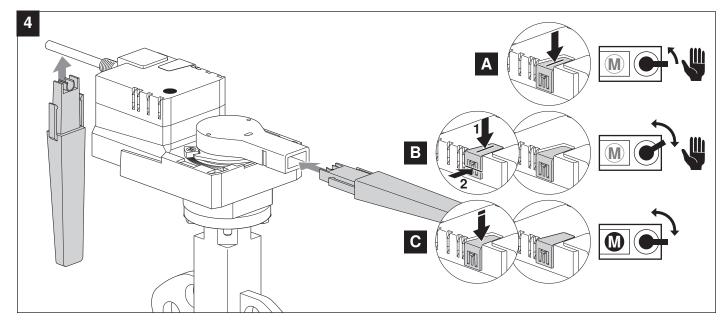
## Check voltage supply connection

- a) 2 Off and 3 On
- Check the supply connections. Possibly **⊥** and **∓** are swapped over.
- **b**) (2) Blinking and (3) Blinking  $\int$  Possibly  $\pm$  and  $\widehat{+}$  are swapped

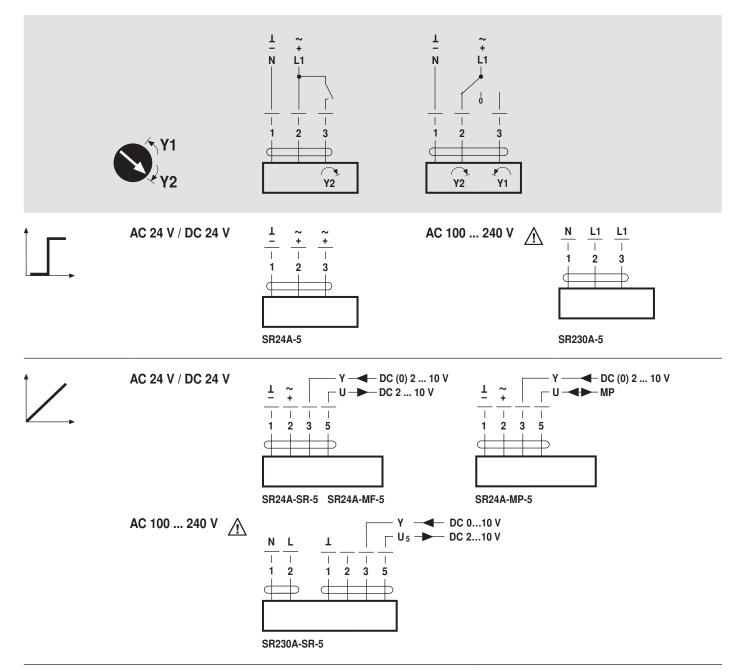


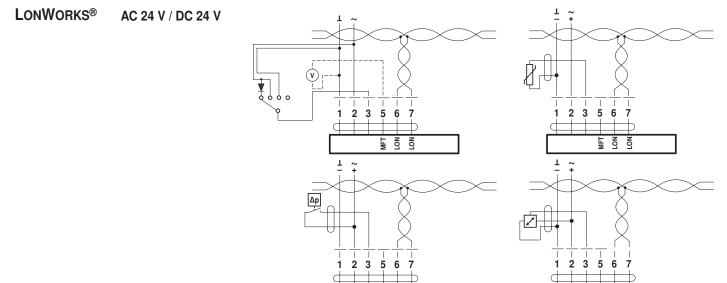
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