## Communication-capable rotary actuator for butterfly valves

- Torque 20 Nm
- Nominal voltage AC/DC 24 V
- Control: Modulating DC 0 ... 10 V or variable
- Position feedback DC 2 ... 10 V or variable
- Communication via BELIMO MP-Bus
- Conversion of sensor signals



## Technical data

## Electrical data

| Nominal voltage | AC $24 \mathrm{~V}, 50 / 60 \mathrm{~Hz} / \mathrm{DC} 24 \mathrm{~V}$ |  |  |
| :---: | :---: | :---: | :---: |
| Power supply range | AC 19.2 ... $28.8 \mathrm{~V} / \mathrm{DC} 21.6$... 28.8 V |  |  |
| Power consumption In operation | 4 W @ nominal torque |  |  |
| At rest | 1.25 W |  |  |
| Rating | 6 VA |  |  |
| Connection | Cable $1 \mathrm{~m}, 4 \times 0.75 \mathrm{~mm}^{2}$ |  |  |
| Functional data | Factory settings | Variable | Settings |
| Torque (nominal torque) | Min. 20 Nm at nominal voltage |  |  |
| Control Control signal $Y$ <br>  <br>  <br> Working range | $\begin{aligned} & \text { DC } 0 \ldots 10 \mathrm{~V} \text {, input impedance } 100 \mathrm{k} \Omega \\ & \text { DC } 2 \ldots 10 \mathrm{~V} \end{aligned}$ | $\begin{array}{ll}\text { Open-close, 3-point (AC only) } \\ \text { Starting point } & \text { DC } 0.5 \ldots 30 \mathrm{~V} \\ \text { End point } & \text { DC } 2.5 \ldots 32 \mathrm{~V}\end{array}$ | $\cdots$ |
| Position feedback (measuring voltage U) | DC 2 ... 10 V , max. 0.5 mA | Starting point $\mathrm{DC} 0.5 \ldots 8 \mathrm{~V}$ <br> End point $\mathrm{DC} 2.5 \ldots 10 \mathrm{~V}$ |  |
| Uni-rotation | $\pm 5 \%$ absolute |  |  |
| Running time | $90 \mathrm{~s} / 90^{\circ}$ ¢ | $90 . . .346 \mathrm{~s}$ |  |
| Automatic adjustment of running time, operating range and measuring signal U to match the mechanical angle of rotation | Manual triggering of the adaption by pressing the "Adaption" button or with the PC-Tool | Automatic adaptation whenever the supply voltage is switched on, or manual triggering |  |
| Angle of rotation limiting | MAX (maximum position) $=100 \%$ <br> MIN (minimum position) $=0 \%$ <br> ZS (intermediate position, only AC) $=50 \%$ | $\begin{aligned} & \text { MAX }=\left(\text { MIN }+30^{\circ} \Varangle\right) \ldots 100 \% \\ & \text { MIN }=0 \% \ldots\left(\text { MAX }-30^{\circ} \Varangle\right) \\ & Z S=\text { MIN } \ldots \text { MAX } \end{aligned}$ |  |
| Sound power level | Max. 45 dB (A) | with a running time of $90 \mathrm{~s}=45$ $\mathrm{dB}(\mathrm{A}) \quad 346 \mathrm{~s}=35 \mathrm{~dB}(\mathrm{~A})$ |  |
| Position indication | Mechanical, plug-on |  |  |
| Safety |  |  |  |
| Protection class | III Safety extra-low voltage |  |  |
| Degree of protection | IP54 in all mounting positions |  |  |
| EMC | CE according to 89/336/EEC |  |  |
| Mode of operation | Type 1 (in acc. with EN 60730-1) |  |  |
| Rated impulse voltage | 0.8 kV (in acc. with EN 60730-1) |  |  |
| Control pollution degree | 3 (in acc. with EN 60730-1) |  |  |
| Ambient temperature range | $+0 \ldots+50^{\circ} \mathrm{C}$ |  |  |
| Media temperature | $-20 \ldots+100^{\circ} \mathrm{C}$ in the butterfly valve |  |  |
| Non-operating temperature range | $-40 \ldots+80^{\circ} \mathrm{C}$ |  |  |
| Ambient humidity range | 95\% RH, non-condensating (acc. to EN 60730-1) |  |  |
| Maintenance | Maintenance-free |  |  |
| Dimensions / weight |  |  |  |
| Dimensions | See "Dimensions" on page 5 |  |  |
| Weight | approx. 1,200 g |  |  |

- The actuator has been designed for use in stationary heating, ventilation and air conditioning systems and is not allowed to be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- It may only be installed by suitably trained personnel. All applicable legal or institutional installation regulations must be complied with.
- The switch for changing the direction of rotation may only be operated by authorised personnel. The direction of rotation must not be reversed in a frost protection circuit.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- The cable is not allowed to be removed from the unit.
- The device contains electrical and electronic components and is not allowed to be disposed of as household refuse. The local and currently valid regulations and requirements must be observed.


## Product features

## Mode of operation

Conventional operation: The actuator is controlled with a standard modulating signal of DC $0 \ldots 10 \mathrm{~V}$ and travels to the position defined by the control signal. Measuring voltage U serves for the electrical display of the actuator position $0 \ldots 100 \%$ and as slave control signal for other actuators.
Operation on the MP-Bus: The actuator receives its digital positioning signal from the higher level controller via the MP-Bus and travels to the position defined. Connection U serves ascommunication interface and does not supply an analogue measuring voltage.

Converter for sensors Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analog/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.

Parameterisable actuators The factory settings cover the most common applications. Input and output signals and other parameters can be altered with the MFT-H parameterising device or the BELIMO Service Tool, MFT-P.

Simple direct mounting Straightforward direct mounting on the butterfly valve with ISO 5211-F05 mounting flange. Themounting position in relation to the butterfly valve can be selected in $90^{\circ}<$ steps.

Manual override Manual adjustment possible with pushbutton - temporary, permanent.The gear is disengaged and the actuator decoupled for as long as the button is pressed / latched.

Adjustable angle of rotation Adjustable angle of rotation with mechanical end stops.
High functional reliability The actuator is overload-proof, requires no limit switches and automatically stops when the end stop is reached.

ISO 5211 - F05Butterfly valve D6.. For BELIMO F05 butterfly valve D6 and other dampers with the following mechanical specifications:

- Square stem head ( 14 mm ) for form-fit attachment of the rotary actuator.
- Hole circle ( $\mathrm{d}=50 \mathrm{~mm}$ ) for assembly with the butterfly valve.

Home position When the supply voltage is switched on for the first time, i.e. at commissioning or after pressing the "gear disengagement" switch, the actuator travels to the home position. Factory setting is Y2 (counter-clockwise rotation). The actuator then moves into the position defined by the control signal.

| Rotary actuator | Rotary valve |
| :---: | :--- |
| $\Upsilon \mathrm{Y} 2$ | $\mathrm{~A}-\mathrm{AB}=0 \%$ |
| Y 1 | $\mathrm{~A}-\mathrm{AB}=100 \%$ |

The actuator then moves into the position defined by the control signal.

## Accessories

|  | Description | Data sheet |
| :--- | :--- | :--- |
| Electrical accessories | Auxiliary switch S..A.. | T2 - S..A.. |
|  | Feedback potentiometer P..A.. | T2 - P.A.. |
|  | Manual parameterising device MFT-H | T2 - MFT-H |
| PC-Tool MFT-P | T2 - MFT-P |  |

## Electrical installation

## Wiring diagram Conventional operation <br> Operation on the MP-Bus



Functions when operated on MP-Bus

Connection on the MP-Bus


Supply and communicationone and the same 3 -wire cable

- no shielding or twisting necessary
- no terminating resistors required


## Power topology

There are no restrictions for the network topology (star, ring, tree or hybrid forms are permitted).


Connection of active sensors


Connection of external switching contact


Connection of passive sensors


| Sensor | Temperature range | Resistance range | Resolution |
| :--- | :---: | :---: | :---: |
| Ni1000 | $-28 \ldots+98^{\circ} \mathrm{C}$ | $850 \ldots 1600 \Omega$ | $1 \Omega$ |
| PT1000 | $-35 \ldots+155^{\circ} \mathrm{C}$ | $850 \ldots 1600 \Omega$ | $1 \Omega$ |
| NTC | $-10 \ldots+160^{\circ} \mathrm{C}$ <br> (depending on the type) | $200 \Omega \ldots 60 \mathrm{k} \Omega$ | $1 \Omega$ |

Functions with basic values (only in conventional mode)

Override control with AC 24 V
with relay contacts


Remote control 0 ... $100 \%$


Master/Slave control (position-dependent)


## Position indication



Override control with AC 24 V with rotary control switch


Minimum limit


Control with 4 ... 20 mA via external resistance


## Functional check



## Procedure

- Apply AC 24 A to connection 1 and 2
- Disconnect connection 3:
- For direction of rotation Y1:

Actuator turns in the direction of

- For direction of rotation Y2:

Actuator turns in the direction of

- Short circuit connections 2 and 3:
- Actuator runs in the opposite direction

Functions for actuators with specific parameters
Override control and limiting with AC 24 V with relay contacts

| Funktionen | a | b | c |
| :--- | :---: | :---: | :---: |
| CLOSE $^{1)}$ | 七 | $-\mathbf{c}$ | - |
| OPEN | - | - | - |
| Control mode in <br> acc. with $Y$ | - | - | Ł |

${ }^{1)}$ Caution! This function is only guaranteed if the start point of the operating range is defined as min. 0.6 V .


## Dimensions [mm]



## Operating controls and indicators


(1) Direction of rotation switch

Switching over: Direction of rotation changes
(2) Pushbutton and green LED display

| Off: | No voltage supply or fault |
| :--- | :--- |
| Green, on: | OperationPress button: <br> Switches on angle of rotation adaptation followed by standard operation |
|  |  |

(3) Pushbutton and yellow LED display

Off: $\quad$ Normal operation without MP-Bus
Yellow, on: Adaptation or synchronising process active
Yellow, flashing: Addressing request sent to MP master
Press button: Confirmation of addressing
Yellow, flickering: MP communication active
(4) Gear disengagement switch

Press button: Gear disengaged, motor stops, manual operation possible Release button: Gear engaged, synchronisation starts, followed by standard operation
(5) Service plug

For connecting parameterising and service tools


2


R6..W..


4

B

C
(1) To


LONWORKS ${ }^{\circledR} \quad$ AC 24 V / DC 24 V


