

**Technical data sheet** 

AVK24A-MP-RE



Communicative globe valve actuator with emergency control function for 2-way and 3-way globe valves

- Actuating force 2000 N
- Nominal voltage AC/DC 24 V
- Control Modulating DC (0)2...10 V Variable
- Nominal stroke 32 mm
- Communication via BELIMO MP-Bus
- Conversion of sensor signals
- Design life SuperCaps: 15 years





## **Technical data**

| Electrical data | Nominal voltage                              | AC/DC 24 V  |  |
|-----------------|--|---|--|
|                 | Nominal voltage frequency                    | 50/60 Hz  |  |
|                 | Nominal voltage range                        | AC 19.228.8 V / DC 21.628.8 V                           |  |
|                 | Power consumption in operation               | 5 W   |  |
|                 | Power consumption in rest position           | 2 W   |  |
|                 | Power consumption for wire sizing            | 9.5 VA  |  |
|                 | Connection supply / control                  | Terminals 4 mm <sup>2</sup> (cable Ø 410 mm)            |  |
|                 | Parallel operation                           | Yes (note the performance data)                         |  |
| Functional data | Actuating force                              | 2000 N  |  |
|                 | Positioning signal Y                         | DC 010 V  |  |
|                 | Positioning signal Y note                    | Input impedance 100 kΩ                                  |  |
|                 | Control signal Y variable                    | Open-close  |  |
|                 |  | 3-point (AC only)                                       |  |
|                 |  | Modulating (DC 032 V)                                   |  |
|                 | Operating range Y                            | DC 210 V  |  |
|                 | Operating range Y variable                   | Start point DC 0.530 V                                  |  |
|                 |  | End point DC 2.532 V                                    |  |
|                 | Position feedback U                          | DC 210 V  |  |
|                 | Position feedback U note                     | Max. 0.5 mA   |  |
|                 | Position feedback U variable                 | Start point DC 0.58 V                                   |  |
|                 | 0. with (2022)                               | End point DC 2.510 V                                    |  |
|                 | Setting emergency position (POP)             | Actuator spindle 0100%, adjustable (POP                 |  |
|                 | Dridging time (DE) veriable                  | rotary button)  |  |
|                 | Bridging time (PF) variable                  | 110 s<br>5% absolute                                    |  |
|                 | Position accuracy<br>Manual override         |   |  |
|                 |  | Gear disengagement with push-button                     |  |
|                 | Nominal stroke                               | 32 mm<br>150 s / 32 mm                                  |  |
|                 | Actuating time                               | 90150 s / 32 mm   |  |
|                 | Actuating time variable                      | 35 s / 32 mm  |  |
|                 | Actuating time emergency control<br>function |   |  |
|                 | Adaption setting range                       | manual (automatic on first power-up)                    |  |
|                 | Adaption setting range variable              | No action   |  |
|                 |  | Adaption when switched on                               |  |
|                 |  | Adaption after pushing the gear disengagement<br>button |  |
|                 | Override control                             | MAX (maximum position) = 100%                           |  |
|                 |  | MIN (minimum position) = $0\%$                          |  |
|                 |  | ZS (intermediate position, AC only) = $50\%$            |  |
|                 | Override control variable                    | MAX = (MIN + 33%)100%                                   |  |
|                 |  | MIN = 0%(MAX – 33%)                                     |  |
|                 |  | ZS = MINMAX   |  |
|                 | Sound power level motor                      | 60 dB(A)  |  |
|                 | Sound power level emergency control position | 60 dB(A)  |  |
|                 | Position indication                          | Mechanically, 532 mm stroke                             |  |
| Safety          | Protection class IEC/EN                      | III Safety extra-low voltage                            |  |
|                 | Degree of protection IEC/EN                  | IP54  |  |
|                 | EMC  | CE according to 2004/108/EC                             |  |

| AVK24A-MP-RE     |                 | Globe valve actuator, communica<br>DC 24 V, 2000 N  | ative, Modulating, AC/  |
|------------------|-----------------|---|---|
| Technical data   |                 |   |   |
|                  | Safety          | Certification IEC/EN<br>Mode of operation<br>Rated impulse voltage supply / control<br>Control pollution degree<br>Ambient temperature<br>Non-operating temperature<br>Ambient humidity<br>Maintenance  | IEC/EN 60730-1 and IEC/EN 60730-2-14           Type 1.AA           0.8 kV           3           050°C           -4080°C           95% r.h., non-condensing           Maintenance-free |
|                  | Weight          | Weight approx.  | 7.6 kg  |
|                  | Terms           | Abbreviations   | POP = Power off position / emergency setting<br>position<br>CPO = Controlled power off / controlled<br>emergency control function<br>PF = Power fail delay time / bridging time       |
| Safety notes     |                 |   |   |
|                  |                 | <ul> <li>This device has been designed for use in stationary heating, ventilation and air conditioning systems and is not allowed to be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.</li> <li>Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.</li> <li>The switch for changing the direction of motion and so the closing point may be adjusted only by authorised specialists. The direction of motion is critical, particularly in connection with frost protection circuits.</li> <li>The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.</li> <li>The device contains electrical and electronic components and is not allowed to be disposed of as household refuse. All locally valid regulations and requirements must be observed.</li> </ul> |   |
| Product features |                 |   |   |
| Mod              | le of operation |   |   |

Operation on the MP-Bus:

The actuator receives its digital positioning signal from the higher level controller via the MP-Bus and travels to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.



# **Product features**

Pre-charging time (start up)

The capacitor actuators require a pre-charging time. This time is used for charging the capacitors up to a usable voltage level. This ensures that, in the event of an electricity interruption, the actuator can move at any time from its current position into the preset emergency setting position (POP).

The duration of the pre-charging time depends mainly on following factors:

- Duration of the electricity interruption
- PF delay time (bridging time)

Typical pre-charging time

0

2

5

10

5

8

12

8

9

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15

10

11

13

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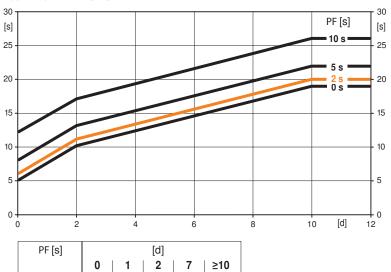
[s]

15

16

18

22



| Delivery condition (capacitors)                                |
|--|
| 14 s after the electricity has been reconnected (see graphic). |
| at 5 s, the actuator requires a pre-charging time of           |
| interruption of 3 days and a bridging time (PF) set            |
| Calculation example: Given an electricity                      |
| PF[s] = Bridging time  |
| [s] = Pre-charging time in seconds                             |
| [d] = Electricity interruption in days                         |

**Converter for sensors** 

Parameterisable actuators

The actuator is completely discharged after delivery from the factory, which is why the actuator requires approximately 20 s pre-charging time before initial commissioning in order to bring the capacitors up to the required voltage level.

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Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.

The factory settings cover the most common applications. Input and output signals and other parameters can be altered with the PC-Tool MFT-P or with the Service tool ZTH EU.

Installation on third-party valves The retrofit actuators for installation on a wide range of valves from various manufacturers are comprised of an actuator, universal valve neck adapter and universal valve stem adapter. Adapt the valve neck and valve stem to begin with, then attach the retrofit actuator to the valve neck adapter, connect to the valve and start up. The valve neck adapter/actuator can be rotated through 360° on the valve neck, provided it is permitted by the size of the installed valve. Installation on BELIMO valves Please use standard actuators from Belimo for installation on Belimo globe valves. The installation of retrofit actuators on Belimo globe valves is technically possible. Manual override Manual control with push-button possible - temporary. The gear is disengaged and the actuator decoupled for as long as the button is pressed. The stroke can be adjusted by using a hexagon socket screw key (5 mm), which is inserted into the top of the actuator. The stroke spindle extends when the key is rotated clockwise. High functional reliability The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

The stroke is indicated mechanically on the bracket with tabs. The stroke range **Position indication** adjusts itself automatically during operation.

| AVK24A-MP-RE                           | Globe valve actuator, communicative, Modulating, AC/<br>DC 24 V, 2000 N  |  |
|--|--|--|
| Product features                       |  |  |
| Home position                          | Factory setting: Actuator spindle is retracted.<br>The first time the supply voltage is switched on, i.e. at the time of commissioning,<br>the actuator carries out an adaption, which is when the operating range and position<br>feedback adjust themselves to the mechanical setting range.<br>The actuator then moves into the position defined by the positioning signal.   |  |
| Direction of stroke switch             | When actuated, the direction of stroke switch changes the running direction in normal operation. The direction of stroke switch has no influence on the emergency setting position (POP) which has been set.   |  |
| Adaption and synchronisation           | <ul> <li>An adaption can be triggered manually by pressing the "Adaption" button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range).</li> <li>Automatic synchronisation after pressing the gearbox disengagement button is configured. The synchronisation is in the home position (0%).</li> <li>The actuator then moves into the position defined by the positioning signal.</li> <li>A range of settings can be adapted using the PC-Tool (see MFT-P documentation)</li> </ul>  |  |
| Rotary knob emergency setting position | The «Emergency setting position» rotary knob can be used to adjust the desired emergency setting position (POP). In the event of an electricity interruption, the actuator will move into the selected emergency setting position, taking into account the bridging time (PF) of 2 s which was set ex-works.<br>Settings: The rotary knob must be set to the «Tool» position for retroactive settings of the emergency setting position with the BELIMO service tool MFT-P. Once the rotary knob is set back to the range 0100%, the manually set value will have positioning authority  |  |
| Bridging time (PF)                     | Electricity interruptions can be bridged up to a maximum of 10 s.<br>In the event of an electricity interruption, the actuator will remain stationary in<br>accordance with the set bridging time. If the electricity interruption is greater than the<br>set bridging time, then the actuator will move into the selected emergency setting<br>position (POP).<br>The bridging time set ex-works is 2 s. This can be modified on site in operation with<br>the use of the BELIMO service tool MFT-P.<br>Settings: The rotary knob must not be set to the «Tool» position!<br>Only the values need to be entered for retroactive adjustments of the bridging time<br>with the BELIMO service tool MFT-P. |  |

# Accessories

|                        | Description  | Туре       |
|------------------------|--|------------|
| Gateways               | Gateway MP for BACnet MS/TP, AC/DC 24 V                                  | UK24BAC    |
|                        | Gateway MP to Modbus RTU, AC/DC 24 V                                     | UK24MOD    |
|                        | Gateway MP for LonWorks®, AC/DC 24 V, LonMark-certified                  | UK24LON    |
|                        | Gateway MP to KNX/EIB, AC/DC 24 V, EIBA certified                        | UK24EIB    |
|                        | Description  | Туре       |
| Electrical accessories | Connecting cable 5 m, A+B: RJ12 6/6, To ZTH/ZIP-USB-MP                   | ZK1-GEN    |
|                        | Connection cable 5 m, A: RJ11 6/4, B: Free wire end, To ZTH/ZIP-USB-MP   | ZK2-GEN    |
|                        | MP-Bus power supply for MP actuators, AC 230/24V for local power supply  | ZN230-24MP |
|                        | Connecting board MP bus suitable for wiring boxes EXT-WR-FPMP            | ZFP2-MP    |
|                        | Auxiliary switch, 2 x SPDT, add-on                                       | S2A-H      |
|                        | Description  | Туре       |
| Service Tools          | Service Tool, for MF/MP/Modbus/LonWorks actuators and VAV-<br>Controller | ZTH EU     |
|                        | Belimo PC-Tool, software for adjustments and diagnostics                 | MFT-P      |
|                        | Adapter to Service-Tool ZTH  | MFT-C      |

## Globe valve actuator, communicative, Modulating, AC/ DC 24 V, 2000 N



# **Electrical installation**



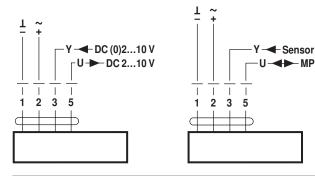
Notes · Connection via safety isolating transformer. · Parallel connection of other actuators possible. Observe the performance data. · Direction of stroke switch factory setting: Actuator spindle retracted.

## Wiring diagrams

AC/DC 24 V, modulating

Operation on the MP-Bus

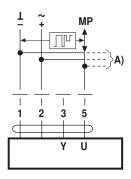
- MP



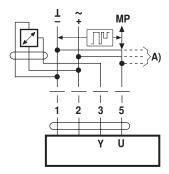
## **Functions**

#### Functions when operated on MP-Bus

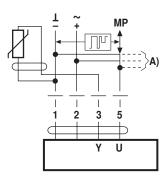
Connection on the MP-Bus



Connection of active sensors



Connection of passive sensors



| Ni1000 | –28+98°C                | 8501600 Ω <sup>2)</sup>  |
|--------|-------------------------|--------------------------|
| PT1000 | –35+155°C               | 8501600 Ω <sup>2)</sup>  |
| NTC    | -10+160°C <sup>1)</sup> | 200 Ω60 kΩ <sup>2)</sup> |

A) more actuators and sensors

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Supply AC/DC 24 V

(max. DC 0...32 V)

· Resolution 30 mV

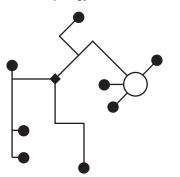
Output signal DC 0...10 V

(max.8)

(max.8)

A) more actuators and sensors (max.8) 1) Depending on the type

2) Resolution 1 Ohm

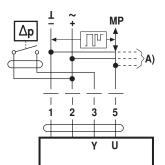


Power topology

There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted). Supply and communication in one and the same 3-wire cable • no shielding or twisting necessary

• no terminating resistors required

Connection of external switching contact



A) more actuators and sensors (max.8)

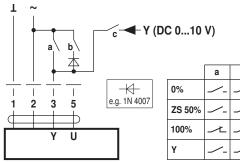
 Switching current 16 mA @ 24 V · Start point of the operating range must be parameterised on the MP actuator as  $\ge 0.5 \text{ V}$ 

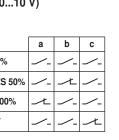


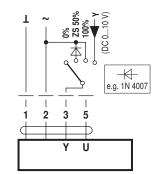
# **Functions**

## Functions with basic values (conventional mode)

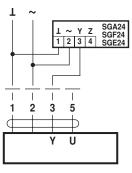
Override control with AC 24 V with relay contacts

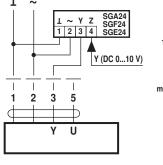




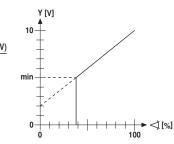


Remote control 0...100% with positioner SG..

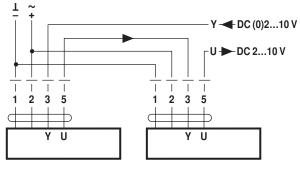




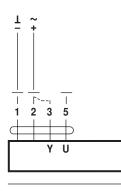
Minimum limit with positioner SG..



Follow-up control (position-dependent)

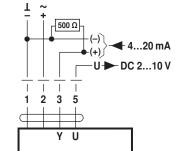


Functional check



#### Procedure

- 1. Apply 24 V to connection 1 and 2
- 2. Disconnect connection 3: - with upwards direction of motion:
- closing point at top - with downwards direction of
- motion: closing point at bottom
- 3. Short circuit connections 2 and 3:
- Actuator runs in the opposite
- direction



Control with 4...20 mA via external resistor

Caution:

DC 2...10 V.

signal DC 2...10 V

The operating range must be set to

4...20 mA current signal to a voltage

The 500  $\Omega$  resistor converts the

## Override control with AC 24 V with rotary switch

# AVK24A-MP-RE



# Functions

# Functions for actuators with specific parameters (Parametrisation with PC-Tool necessary)

d

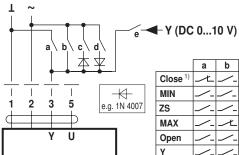
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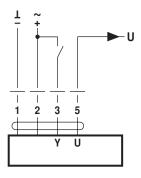
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Override control and limiting with AC 24 V with relay contacts



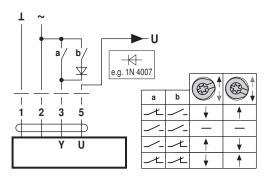
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Control open-close

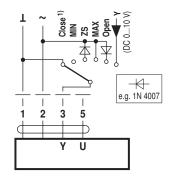


Control 3-point

b с



Override control and limiting with AC 24 V with rotary switch



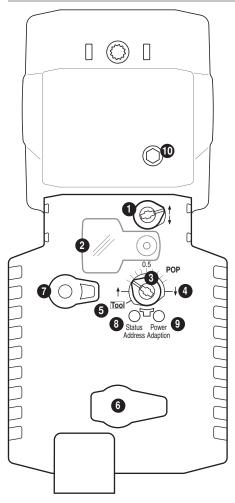
1) **Caution:** This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.

# AVK24A-MP-RE

Globe valve actuator, communicative, Modulating, AC/ DC 24 V, 2000 N



# **Operating controls and indicators**



| 1 | Direction of stroke switch |                             |  |
|---|----------------------------|-----------------------------|--|
|   | Switch over:               | Direction of stroke changes |  |
| 2 | Cover, POP button          |                             |  |

- **3** POP button
- 4 Scale for manual adjustment
- 5 Position for adjustment with tool
- 6 Service plug

For connecting the parameterisation and service tools

Gear disengagement button
 Press button: Gear disengaged, motor stops, manual override possible
 Release button: Gear engaged, standard mode

| LED displays<br>green |          | Meaning / function   |
|-----------------------|----------|--|
| Off                   | On       | Operation OK   |
| Off                   | Flashing | POP function active  |
| On                    | Off      | Pre-charging time SuperCap,<br>Fault SuperCap or<br>wiring error in supply |
| Off                   | Off      | Not in operation   |
| On                    | On       | Adaptation process active  |
| Flickering            | On       | Communication active   |

#### 8 Push-button (LED yellow)

Press button: Confirmation of addressing

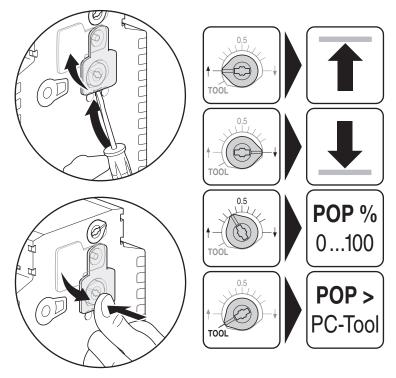
9 Push-button (LED green)

Press button Triggers stroke adaptation, followed by standard mode

### Manual override

Clockwise: Actuator spindle extends Counterclockwise: Actuator spindle retracts

## Emergency position (POP) setting



# Globe valve actuator, communicative, Modulating, AC/ DC 24 V, 2000 N

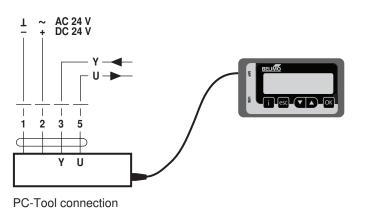


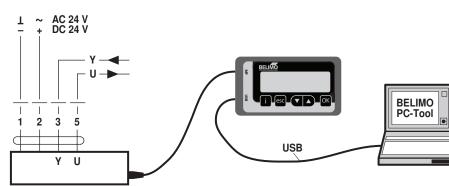
# Service



Notes • The actuator can be parameterised by PC-Tool and ZTH EU via the service socket.

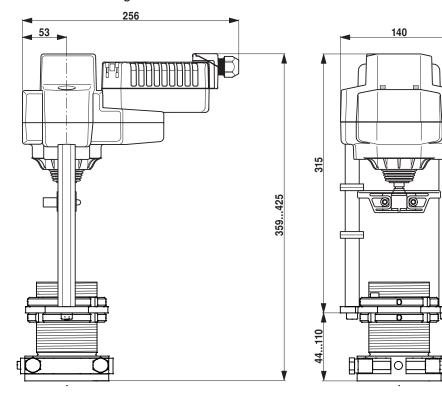
ZTH EU connection





# **Dimensions** [mm]

**Dimensional drawings** 





**Further documentation** 

· Installation instructions for actuators